

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	1	(specific and point and detect\$4 and target and viewpoint and parameters).CLM.	US-PGPU B	AND	ON	2005/07/21 16:43

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L1	6033	((382/100,181,190,200,201) or (351/209,210) or (348/38,39,42,43,44,46,47,151)).CCLS.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/07/21 15:00
L2	4908	1 and (detect\$4 or recogni\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/07/21 15:00
L3	3912	2 and (featur\$4 or pictur\$4 or photograph\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/07/21 15:44
L4	2805	3 and (camera\$4 or video\$4 or captur\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/07/21 15:41

L5	2616	4 and (estimat\$4 or calculat\$4 or measur\$4 or comput\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:35
L6	871	5 and target\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:41
L7	612	6 and extract\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:43
L8	563	7 and stor\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:37
L9	397	8 and parameter\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:42

L10	266	9 and (orient\$4 or orientation)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:43
L11	24	10 and (specific\$4 near4 point\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:40
L12	3	11 and viewpoint\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:39
L13	3051	((detect\$4 or scan\$4 or recogni\$4) near5 (specific\$4 near4 point\$4))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:42
L14	161	estimat\$4 near4 viewpoint\$3	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:41

L15	86	14 and (camera\$4 or video\$4 or captur\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:41
L16	34	15 and target\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:41
L17	1	16 and ((detect\$4 or scan\$4 or recogni\$4) near5 (specific\$4 near4 point\$4))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:42
L18	896	13 and parameter\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:42
L19	388	18 and extract\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:43

L20	349	19 and (featur\$4 or pictur\$4 or photograph\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:43
L21	165	20 and (orient\$4 or orientation)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:43
L22	71	21 and templat\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:44
L23	71	22 and compar\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/07/21 15:45

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IEEE JNL IEEE Journal or Magazine

IEEE JNL IEEE Journal or Magazine

IEEE CNF IEEE Conference Proceeding

IEEE CNF IEEE Conference Proceeding

IEEE STD IEEE Standard

**1. Virtual Reality Technology**

Burdea, G. C.; Coiffet, P.;

June 2003 Page(s):464

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» Key

IEEE JNL IEEE Journal or Magazine

IEEE JNL IEE Journal or Magazine

IEEE CNF IEEE Conference Proceeding

IEEE CNF IEE Conference Proceeding

IEEE STD IEEE Standard

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Application#	Patent#	Status	Date Filed	Title	Inventor Name
11127000	Not Issued	020	05/11/2005	INFORMATION PROCESSING METHOD AND DEVICE	SATOH, KIYOHIDE
11126919	Not Issued	020	05/11/2005	INFORMATION PROCESSING METHOD AND SYSTEM	SATOH, KIYOHIDE
11126916	Not Issued	020	05/11/2005	MARKER PLACEMENT INFORMATION ESTIMATING METHOD AND INFORMATION PROCESSING DEVICE	SATOH, KIYOHIDE
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10952876	Not Issued	030	09/30/2004	DATA CONVERSION METHOD AND APPARATUS, AND ORIENTATION MEASUREMENT APPARATUS	SATOH, KIYOHIDE
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<u>10351326</u>	Not Issued	092	01/27/2003	POSITION AND ORIENTATION DETERMINATION METHOD AND APPARATUS AND STORAGE MEDIUM	SATOH, KIYOHIDE
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<u>09817037</u>	Not Issued	071	03/27/2001	SPECIFIC POINT DETECTING METHOD AND DEVICE	SATOH, KIYOHIDE
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